

Classification: Part 2



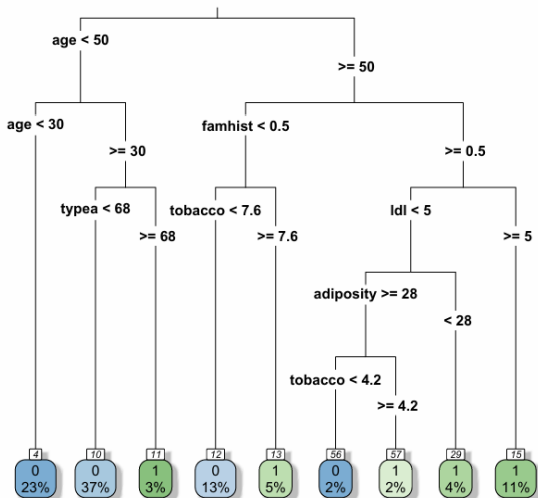
Yuling Yan

University of Wisconsin-Madison, Fall 2024

Tree-based methods

Classification tree

South African heart disease data: "0"="Yes, Disease", "1"="No"



Classification tree

Setup: $\mathcal{X} = \mathbb{R}^d$, $\mathcal{Y} = \{1, \dots, K\}$, training data $(X_1, Y_1), \dots, (X_n, Y_n)$

Idea: grow a tree to recursively partition the feature space into a set of rectangles, and do a simple majority vote in each rectangle

- Each node represents a rectangle in the feature space. The root node is the feature space $\mathcal{X} = \mathbb{R}^d$
- Each node is either a leaf (no children) or a parent (has two children)
- The left and right children comes from a partition of their parent node
- Suppose we have a collection of final partitioned regions associated with the leaves at the bottom of the tree, denoted by R_1, \dots, R_M
- For any input x , suppose that $x \in R_j$, then this classification tree returns

$$\hat{f}(x) = \arg \max_{k \in \mathcal{Y}} \sum_{X_i \in R_j} \mathbb{1}\{Y_i = k\}$$

i.e., the predicted label is the majority in the region R_j

How to grow a classification tree?

In order to grow a classification tree, we need to ask:

1. How to split each parent node?
2. How large should we grow the tree?

For the first question: **minimizing impurity**

- Suppose that the parent node is associated with a rectangle R
- Choose a covariate X_j and a split point t that minimizes the impurity
- Let the rectangles associated with its left and right children be

$$R_1(j, t) = \{X \in R : X_j \leq t\} \quad \text{and} \quad R_2(j, t) = \{X \in R : X_j > t\},$$

For the second question: **set some stopping criteria.**

- For example, we may fix some number n_0 , and we might stop partition a node when its associated rectangle has fewer than n_0 training data points.

Impurity function

Let R be the node to be split into two regions. We choose

$$\arg \min_{j,t} \underbrace{\frac{|R_1(j,t)|}{|R|} \gamma(R_1(j,t)) + \frac{|R_2(j,t)|}{|R|} \gamma(R_2(j,t))}_{\text{impurity function}},$$

- Here $\gamma(R)$ measures the “variance” of the labels of data in R : we want

$$\{Y_i : X_i \in R\} \quad \text{to have low variability}$$

- For any given rectangle R , let

$$p_k = \frac{1}{|R|} \sum_{X_i \in R} \mathbb{1}\{Y_i = k\}, \quad 1 \leq k \leq K.$$

Two common choice of the function $\gamma(\cdot)$:

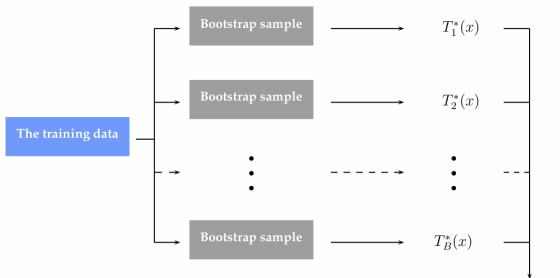
- **Gini index:** $\gamma(R) = \sum_k p_k(1 - p_k)$
- **Cross entropy:** $\gamma(R) = - \sum_k p_k \log p_k$

Insights

- **advantage:** the tree structure provides great **interpretability**
 - for example, it allows reasoning about the cause of diseases
- **disadvantage:** **instability** due to the use of *greedy* search:
 - splitting process is **greedy**
 - small changes in the training data can lead to **significantly different tree structures**
- **Solutions:**
 - Regularization: controlling tree growth parameters
 - Pruning: removing branches that do not provide significant predictive power
 - **Ensemble Methods:** use bagging to create a random forest

Bootstrap aggregating (Bagging)

- Training data $Z_n = \{(X_i, Y_i), 1 \leq i \leq n\}$
- Bootstrap sample $Z^{(*b)} = \{(X_i^{(*b)}, Y_i^{(*b)}), 1 \leq i \leq n\}$: sample n data points randomly from Z_n with replacement
- Apply the learning algorithm to the bootstrap sample for B times, and produce outcomes \hat{f}_b
- Majority vote: $\hat{f}^{\text{bagging}}(x) = \arg \max_{k \in \mathcal{Y}} \sum_{b=1}^B \mathbb{1}\{\hat{f}_b(x) = k\}$



Insights

- Trees generated in bagging are identically distributed (**not independent!**)
- Bias of bagged trees is the same as the individual tree
- **Pro:** Reduce the variance, so good for high-variance, low-bias procedures, like trees.
- **Heuristics:** Suppose we have B identically distributed random variables with variance σ^2 and positive pairwise correlation ρ , then their average has variance of

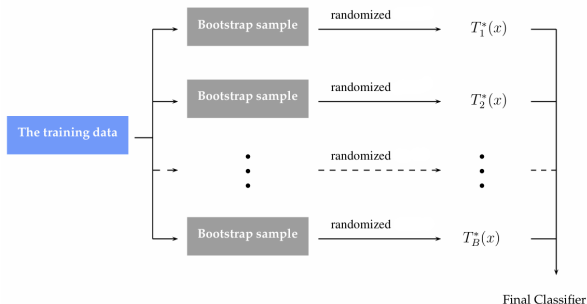
$$\rho\sigma^2 + \frac{1-\rho}{B}\sigma^2$$

- Increasing B does not reduce the first term

— Random Forest!

Random forests

- **Key idea:** use random dropout to decorrelate bootstrapped trees
- When growing a tree on a bootstrapped sample, before each split of the node, select $m \ll d$ variables at random as candidates to split
- Typical values for m is \sqrt{d} .
- Majority vote: $\hat{f}^{\text{RF}}(x) = \arg \max_{k \in \mathcal{Y}} \sum_{b=1}^B \mathbb{1}\{\tilde{f}_b(x) = k\}$



How to remove bias: Boosting

- Setup: $\mathcal{X} = \mathbb{R}^d$, $\mathcal{Y} = \{\pm 1\}$
- Weak classifier: error rate only slightly better than random guess
- Key idea: sequentially apply weak classification algorithm to repeatedly modified versions of the data to produce a sequence of weak classifiers
 - assign unequal weights to training data points
— *possible for trees*
 - sequentially find a committee of weak classifiers $\{\hat{f}_m\}_{m=1}^M$
 - produce the final prediction through a weighted majority vote

$$\hat{f}(x) := \text{sign}\left(\sum_{m=1}^M \alpha_m \hat{f}_m(x)\right)$$

AdaBoost

Initialization: set the weights $w_i = 1/n$ for $1 \leq i \leq n$.

For $m = 1, \dots, M$:

- Fit a weak classifier $\hat{f}_m(x)$ using training data with weights $\omega_1, \dots, \omega_n$
- Compute the weighted misclassification error:

$$\text{err}^{(m)} = \frac{\sum_{i=1}^n w_i \mathbb{1}\{Y_i \neq \hat{f}_m(X_i)\}}{\sum_{i=1}^n w_i}.$$

- Compute:

$$\alpha_m = \log\left(\frac{1 - \text{err}^{(m)}}{\text{err}^{(m)}}\right).$$

- Update the weights by:

$$w_i \leftarrow w_i \cdot \exp\left(\alpha_m \cdot \mathbb{1}\{Y_i \neq \hat{f}_m(X_i)\}\right), \quad i = 1, 2, \dots, n.$$

Output: $\hat{f}(x) = \text{sign}\left(\sum_{m=1}^M \alpha_m \hat{f}_m(x)\right)$.

AdaBoost: insights

Key idea: in the weight update step

$$w_i \leftarrow w_i \cdot \exp(\alpha_m \cdot \mathbb{1}\{Y_i \neq \hat{f}_m(X_i)\}), \quad i = 1, 2, \dots, n.$$

- For incorrectly classified data points, their weights get inflated by e^{α_m}
- Note that $\alpha_m > 0$ should always hold
- This re-weighting encourages the next classifier to focus more on the misclassified data points

Discussion: three main approaches to classification

Three main approaches

Bayes optimal classifier: for any $x \in \mathcal{X}$, output

$$f^*(x) := \arg \max_{y \in \mathcal{Y}} \mathbb{P}(Y = y \mid X = x)$$

minimizes the Bayes risk $R(f) = \mathbb{P}(f(X) \neq Y)$

Three main approaches

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- Plug-in approach: model data distribution ρ , then estimate densities

$$\mathbb{P}(Y = y \mid X = x) = \frac{\mathbb{P}(X = x \mid Y = y) \mathbb{P}(Y = y)}{\sum_{y' \in \mathcal{Y}} \mathbb{P}(X = x \mid Y = y') \mathbb{P}(Y = y')}$$

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Example: LDA, QDA, Kernel density classifier

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- Plug-in approach
- Regression: modeling and estimating each

$$r_k(x) := \mathbb{P}(Y = k \mid X = x) \quad \text{for } k = 1, \dots, K$$

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Example: logistic regression

Three main approaches

Bayes optimal classifier: for any $x \in \mathcal{X}$, output

$$f^*(x) := \arg \max_{y \in \mathcal{Y}} \mathbb{P}(Y = y \mid X = x)$$

minimizes the Bayes risk $R(f) = \mathbb{P}(f(X) \neq Y)$

- Plug-in approach
- Regression
- Empirical risk minimization: choose a set of classifiers \mathcal{F} and find $\hat{f} \in \mathcal{F}$ that minimizes the “empirical risk”:

$$R_n(f) := \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\}$$

Intuition: when n is large, $R_n(f) \approx R(f)$ by LLN

Three main approaches

Bayes optimal classifier: for any $x \in \mathcal{X}$, output

$$f^*(x) := \arg \max_{y \in \mathcal{Y}} \mathbb{P}(Y = y \mid X = x)$$

minimizes the Bayes risk $R(f) = \mathbb{P}(f(X) \neq Y)$

- Plug-in approach
- Regression
- Empirical risk minimization
- Other approaches: SVM, tree-based methods...

ERM: advantages

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\} =: R_n(f)$$

- a straightforward method based on simple heuristics
- can be easily generalized to other loss $\ell(\cdot, \cdot)$ by considering

— *robustness!*

$$R_n(f) := \frac{1}{n} \sum_{i=1}^n \ell(f(X_i), Y_i)$$

if the ultimate goal is to minimize $R_\ell(f) = \mathbb{E}[\ell(f(X), Y)]$. For example, in binary classification (i.e., $\mathcal{Y} = \{0, 1\}$)

- Hinge loss $\ell(f(x), y) = \max\{0, 1 - yf(x)\}$
- Logistic loss $\ell(f(x), y) = \log(1 + \exp(-yf(x)))$

— *Logistic regression can also be viewed as ERM!*

ERM: disadvantages

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\} =: R_n(f)$$

- Not easy to compute (due to nonsmoothness of the indicator function)
- Solution: in binary classification (i.e., $\mathcal{Y} = \{0, 1\}$), consider using hinge loss or logistic loss $\ell(\cdot)$

$$R_n(f) := \frac{1}{n} \sum_{i=1}^n \ell(f(X_i), Y_i)$$

and relax $f : \mathbb{R}^d \rightarrow \mathbb{R}$, and finally output $\text{sign}(2(f(x)) - 1)$

- Here we will only focus on the standard ERM

ERM: error decomposition

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\} =: R_n(f)$$

- We want to control the excess risk

$$R(\hat{f}_n) - R(f^*) = \underbrace{R(\hat{f}_n) - \min_{f \in \mathcal{F}} R(f)}_{\geq 0, \text{ statistical error}} + \underbrace{\min_{f \in \mathcal{F}} R(f) - R(f^*)}_{\geq 0, \text{ approximation error}}$$

- **approximation error**: becomes smaller when choosing larger \mathcal{F}
— *becomes 0 when $f^* \in \mathcal{F}$*
- **statistical error**: becomes smaller when n becomes larger, and when choosing smaller \mathcal{F} (why?)
- **trade-off between fit and complexity**
- In this course, we will focus on understanding **statistical error** with a given \mathcal{F} that includes f^* (so that **approximation error** = 0)

Excess risk via uniform deviations

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\} =: R_n(f)$$

Theorem 3.1

The excess risk is upper bounded by

$$R(\hat{f}_n) - R(f^*) \leq 2 \sup_{f \in \mathcal{F}} |R_n(f) - R(f)|$$

Implications:

- For a given f , we know that $R_n(f) \rightarrow R(f)$ at a rate $O(1/\sqrt{n})$ by CLT

$$\sqrt{n}(R_n(f) - R(f)) \xrightarrow{d} \mathcal{N}(0, \text{var}(\mathbb{1}\{f(X) \neq Y\}))$$

- But what about the **uniform convergence** of $\sup_{f \in \mathcal{F}} |R_n(f) - R(f)|$?

Concentration inequalities and uniform convergence

Why concentration inequalities?

Consider i.i.d. variables X_1, \dots, X_n with $\mathbb{E}[X_i] = \mu$ and $\text{var}(X_i) = \sigma^2$

- Central limit theorem (CLT):

$$\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n X_i - \mu \right) \xrightarrow{d} \mathcal{N}(0, \sigma^2)$$

tells us that the sample average concentrates around μ , and the deviation scales like σ/\sqrt{n} as $n \rightarrow \infty$

- But this does not say anything useful when n is finite
- We want some non-asymptotic statement like:

$$\mathbb{P} \left(\left| \frac{1}{n} \sum_{i=1}^n X_i - \mu \right| \geq \varepsilon(n, \delta) \right) \leq \delta$$

holds for any $\delta > 0$, where $\varepsilon(n, \delta) > 0$ is some quantity that depends on the sample size n and the exceptional probability δ

A simple case with i.i.d. Gaussian

Suppose that $X_1, \dots, X_n \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu, \sigma^2)$, then we have

$$\frac{1}{n} \sum_{i=1}^n X_i - \mu \sim \mathcal{N}\left(0, \frac{\sigma^2}{n}\right)$$

Theorem 3.2

For $G \sim \mathcal{N}(0, 1)$ and any $t > 0$, we have

$$\left(\frac{1}{t} - \frac{1}{t^3}\right) \frac{1}{\sqrt{2\pi}} e^{-t^2/2} \leq \mathbb{P}(G \geq t) \leq \frac{1}{t} \frac{1}{\sqrt{2\pi}} e^{-t^2/2}.$$

As a result,

$$\mathbb{P}\left(\left|\frac{1}{n} \sum_{i=1}^n X_i - \mu\right| \geq t\right) \leq \frac{2\sigma}{\sqrt{nt}} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{nt^2}{2\sigma^2}\right)$$

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Question: how can we extend these to more general distributions?

From Gaussian to sub-Gaussian

- Question: can we generalize these results to other random variables?
- Idea: consider other random variables with similar tail probability
- From Theorem 3.2, we know that for $G \sim \mathcal{N}(0, \sigma^2)$,

$$\mathbb{P}(|G| \geq t) \lesssim e^{-t^2/\sigma^2} \quad \text{for all } t \geq 0$$

- We may consider random variables satisfy this type of tail properties
— *sub-Gaussian*

Sub-Gaussian properties

Let X be a random variable, then the following properties are equivalent:

1. The tails of X satisfy

$$\mathbb{P}(|X| \geq t) \leq 2 \exp(-t^2/K_1^2) \quad \text{for all } t \geq 0$$

2. The moments of X satisfy

$$\|X\|_{L^p} := (\mathbb{E}[|X|^p])^{1/p} \leq K_2 \sqrt{p} \quad \text{for all } p \geq 1$$

3. The moment generating function (MGF) of X^2 satisfies

$$\mathbb{E}[\exp(\lambda^2 X^2)] \leq \exp(K_3^2 \lambda^2) \quad \text{for all } \lambda \text{ such that } |\lambda| \leq 1/K_3$$

4. The MGF of X^2 is bounded at some point, namely

$$\mathbb{E}[\exp(X^2/K_4^2)] \leq 2.$$

5. If $\mathbb{E}X = 0$, then the MGF of X satisfies

$$\mathbb{E}[\exp(\lambda X)] \leq \exp(K_5^2 \lambda^2) \quad \text{for all } \lambda \in \mathbb{R}.$$

where $K_1, \dots, K_5 > 0$ may differ by at most a multiplicative constant factor

Sub-Gaussian distributions: definition

- If X satisfies one of properties 1-4, it is a *sub-Gaussian random variable*.
- The *sub-Gaussian norm* of X , denoted $\|X\|_{\psi_2}$, is defined to be the smallest K_4 in property 4. In other words, we define

$$\|X\|_{\psi_2} = \inf \{t > 0 : \mathbb{E} \exp (X^2/t^2) \leq 2\}.$$

— can also be defined using K_1 , K_2 or K_3

- Properties: there exists some absolute constants $c, C > 0$ such that
 - $P(|X| \geq t) \leq 2 \exp(-ct^2/\|X\|_{\psi_2}^2)$
 - $\|X\|_{L^p} \leq C\|X\|_{\psi_2} \sqrt{p}$
 - $\mathbb{E} \exp(X^2/\|X\|_{\psi_2}^2) \leq 2$
 - if $\mathbb{E}[X] = 0$, then $\mathbb{E} \exp(\lambda X) \leq \exp(C\lambda^2\|X\|_{\psi_2}^2)$

Sub-Gaussian distributions: examples

- **Gaussian:** if $X \sim \mathcal{N}(0, \sigma^2)$, then X is sub-Gaussian with

$$\|X\|_{\psi_2} \leq C\sigma$$

for some universal constant $C = 2\sqrt{2/3}$.

- **Bounded:** any bounded random variable X is sub-Gaussian with

$$\|X\|_{\psi_2} \leq C\|X\|_{\infty}$$

for some universal constant $C = 1/\sqrt{\log 2}$.

Sub-Gaussian norm can be viewed as a characterization of “magnitude” for light tail distributions.

Centering and independent sums

Theorem 3.3

- If X is sub-Gaussian, then $X - \mathbb{E}[X]$ is sub-Gaussian with

$$\|X - \mathbb{E}[X]\|_{\psi_2} \leq C\|X\|_{\psi_2}$$

where C is an absolute constant.

- Let X_1, \dots, X_N be independent, mean zero, sub-Gaussian random variables. Then the sum $S_N = \sum_{i=1}^N X_i$ is also sub-Gaussian, and its sub-Gaussian norm satisfies

$$\|S_N\|_{\psi_2}^2 \leq C \sum_{i=1}^N \|X_i\|_{\psi_2}^2,$$

where C is an absolute constant.

Analog:

- If X_1, \dots, X_n are i.i.d. $\mathcal{N}(0, \sigma^2)$, then $S_N \sim \mathcal{N}(0, N\sigma^2)$
- If X_1, \dots, X_n are independent with $\|X_i\|_{\psi_2} \leq \sigma$, then $\|S_N\|_{\psi_2} \lesssim \sqrt{N}\sigma$

Hoeffding's inequality

Theorem 3.4 (Hoeffding's Inequality)

Let X_1, \dots, X_N be independent, mean-zero, sub-Gaussian random variables. Then, for any $t \geq 0$, we have:

$$\mathbb{P} \left(\left| \sum_{i=1}^N X_i \right| \geq t \right) \leq 2 \exp \left(- \frac{ct^2}{\sum_{i=1}^N \|X_i\|_{\psi_2}^2} \right),$$

where c is an absolute constant.

Implications

- **General Hoeffding:** under the setup of Theorem 3.4, consider any vector $\mathbf{a} = (a_1, \dots, a_n) \in \mathbb{R}^n$, we have

$$\mathbb{P} \left(\left| \sum_{i=1}^N a_i X_i \right| \geq t \right) \leq 2 \exp \left(-\frac{ct^2}{K^2 \|\mathbf{a}\|_2^2} \right),$$

where $K := \max \|X_i\|_{\psi_2}$.

- **Example:** suppose that $X_i \sim \text{Bernoulli}(p_i)$ for $1 \leq i \leq n$, then

$$\mathbb{P} \left(\left| \sum_{i=1}^N (X_i - p_i) \right| \geq t \right) \leq 2 \exp \left(-\frac{ct^2}{N} \right),$$

A sharper result for binomial concentration: Chernoff's inequality (HW)

Back to ERM: finite \mathcal{F}

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\} =: R_n(f)$$

Theorem 3.5

Suppose that \mathcal{F} is a finite set. Then with probability exceeding $1 - \delta$, the excess risk of ERM is upper bounded by

$$R(\hat{f}_n) - R(f^*) \leq C \sqrt{\frac{\log(|\mathcal{F}|/\delta)}{n}}.$$

for some universal constant $C > 0$.

- Key proof idea: **union bound argument**
- What if \mathcal{F} is not finite (e.g., the set of linear classifiers)?

— use *VC dimension!*

Back to ERM: finite \mathcal{F}

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- Key proof idea: **union bound argument**
- What if \mathcal{F} is not finite (e.g., the set of linear classifiers)?
— use *VC dimension!*
- But before going into that, let's first warm up with something simpler

ℓ_2 norm of a sub-Gaussian random vector

- Consider a random vector $\mathbf{x} = (X_1, \dots, X_d)$, where X_1, \dots, X_d are independent random variables with $\mathbb{E}[X_i] = 0$ and $\|X_i\|_{\psi_2} \leq \sigma$
- Can we establish a non-asymptotic upper bound for $\|\mathbf{x}\|_2$?

ℓ_2 norm of a sub-Gaussian random vector

- Consider a random vector $\mathbf{x} = (X_1, \dots, X_d)$, where X_1, \dots, X_d are independent random variables with $\mathbb{E}[X_i] = 0$ and $\|X_i\|_{\psi_2} \leq \sigma$
- Can we establish a non-asymptotic upper bound for $\|\mathbf{x}\|_2$?
- Solution 1: entrywise concentration and union bound

$$\mathbb{P}(\|\mathbf{x}\|_2 \leq C\sigma\sqrt{d\log(d/\delta)}) \geq 1 - \delta$$

for some universal constant $C > 0$

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for some universal constant $C > 0$

- Solution 2: uniform concentration using

$$\|\mathbf{x}\|_2 = \sup_{\mathbf{a} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{x}$$

where $\mathcal{S}^{d-1} := \{\mathbf{x} \in \mathbb{R}^d : \|\mathbf{x}\|_2 = 1\}$ is the unit sphere in \mathbb{R}^d

— *could this provide a better concentration bound?*

Operator norm of sub-Gaussian matrix

- Consider a random matrix $\mathbf{X} = (X_{i,j})_{1 \leq i,j \leq d}$ with independent entries that satisfies $\mathbb{E}[X_{i,j}] = 0$ and $\|X_{i,j}\|_{\psi_2} \leq \sigma$
- Can we establish a non-asymptotic upper bound for $\|\mathbf{X}\|$?
- Operator norm:

$$\|\mathbf{X}\| = \sup_{\mathbf{a} \in \mathcal{S}^{d-1}} \|\mathbf{X}\mathbf{a}\|_2 = \sup_{\mathbf{a}, \mathbf{b} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{X} \mathbf{b}$$

where $\mathcal{S}^{d-1} := \{\mathbf{x} \in \mathbb{R}^d : \|\mathbf{x}\|_2 = 1\}$ is the unit sphere in \mathbb{R}^d

A framework for uniform concentration

- **Goal:** upper bounding $\sup_{\mathbf{a} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{x}$
- **Step 1: pointwise concentration.** For any fixed $\mathbf{a} \in \mathcal{S}^{d-1}$, we can use Hoeffding's inequality to get

$$\mathbb{P}(|\mathbf{a}^\top \mathbf{x}| \leq C\sigma\sqrt{\log(1/\delta)}) \geq 1 - \delta$$

for some universal constant $C > 0$

- **Difficulty:** the unit sphere \mathcal{S}^{d-1} is not a finite set, union bound argument does not work
- **Idea:** find a finite subset \mathcal{N} of \mathcal{S}^{d-1} that is *fine* enough, such that

$$\sup_{\mathbf{a} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{x} \stackrel{?}{\lesssim} \sup_{\mathbf{a} \in \mathcal{N}} \mathbf{a}^\top \mathbf{x} \leq C\sigma\sqrt{\log(|\mathcal{N}|/\delta)}$$

with probability at least $1 - \delta$

Epsilon net

- Let (T, d) be a metric space. Consider a subset $K \subset T$ and let $\varepsilon > 0$.
 - e.g., consider $T = \mathbb{R}^d$, $d(\cdot, \cdot)$ is Euclidean distance, $K = \mathcal{S}^{d-1}$
- A subset $N \subseteq K$ is called an ε -net of K if every point in K is within distance ε of some point of N , i.e.,

$$\forall x \in K, \quad \exists x_0 \in N \quad \text{s.t.} \quad d(x, x_0) \leq \varepsilon.$$

Theorem 3.6

Let \mathcal{N}_ε be an ε -net of \mathcal{S}^{d-1} . If $\varepsilon < 1$, then for any $\mathbf{x} \in \mathbb{R}^d$,

$$\sup_{\mathbf{a} \in \mathcal{N}_\varepsilon} \mathbf{a}^\top \mathbf{x} \leq \sup_{\mathbf{a} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{x} \leq \frac{1}{1-\varepsilon} \sup_{\mathbf{a} \in \mathcal{N}_\varepsilon} \mathbf{a}^\top \mathbf{x},$$

and if $\varepsilon < 1/2$, then for any $\mathbf{X} \in \mathbb{R}^{d \times d}$,

$$\sup_{\mathbf{a}, \mathbf{b} \in \mathcal{N}_\varepsilon} \mathbf{a}^\top \mathbf{X} \mathbf{b} \leq \sup_{\mathbf{a}, \mathbf{b} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{X} \mathbf{b} \leq \frac{1}{1-2\varepsilon} \sup_{\mathbf{a}, \mathbf{b} \in \mathcal{N}_\varepsilon} \mathbf{a}^\top \mathbf{X} \mathbf{b}.$$

The covering number

Covering number: the **smallest** possible cardinality of an ε -net of K , denoted by $\mathcal{N}(K, \varepsilon)$

Theorem 3.7

The covering number of \mathcal{S}^{d-1} is upper bounded by

$$\mathcal{N}(\mathcal{S}^{d-1}, \varepsilon) \leq \left(\frac{2}{\varepsilon} + 1\right)^d$$

ℓ_2 norm of sub-Gaussian random vector

- **Goal:** upper bounding $\sup_{\mathbf{a} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{x}$
- **Step 1: pointwise concentration.** For any fixed $\mathbf{a} \in \mathcal{S}^{d-1}$, we can use Hoeffding's inequality to get

$$\mathbb{P}(|\mathbf{a}^\top \mathbf{x}| \leq C_1 \sigma \sqrt{\log(1/\delta)}) \geq 1 - \delta$$

for some universal constant $C_1 > 0$

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- **Step 2: uniform concentration over an $1/2$ -net.** Let $\mathcal{N}_{1/2}$ be the smallest $1/2$ -net of \mathcal{S}^{d-1} . By union bound argument and Theorem 3.7,

$$\mathbb{P}\left(\sup_{\mathbf{a} \in \mathcal{N}_{1/2}} |\mathbf{a}^\top \mathbf{x}| \leq C_2 \sigma \sqrt{d \log(1/\delta)}\right) \geq 1 - \delta$$

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for some universal constant $C_2 > 0$

- **Step 3: approximation.** By Theorem 3.6,

$$\mathbb{P}(\|\mathbf{x}\|_2 \leq C_3 \sigma \sqrt{d \log(1/\delta)}) \geq 1 - \delta$$

for some universal constant $C_3 > 0$

Operator norm of sub-Gaussian random matrix

- **Goal:** upper bounding $\sup_{\mathbf{a}, \mathbf{b} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{X} \mathbf{b}$
- **Step 1: pointwise concentration.** For any fixed $\mathbf{a}, \mathbf{b} \in \mathcal{S}^{d-1}$, we can use Hoeffding's inequality to get

$$\mathbb{P}(|\mathbf{a}^\top \mathbf{X} \mathbf{b}| \leq C_1 \sigma \sqrt{\log(1/\delta)}) \geq 1 - \delta$$

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- **Step 2: uniform concentration over an $1/4$ -net.** Let $\mathcal{N}_{1/4}$ be the smallest $1/4$ -net of \mathcal{S}^{d-1} . By union bound argument and Theorem 3.7,

$$\mathbb{P}\left(\sup_{\mathbf{a}, \mathbf{b} \in \mathcal{N}_{1/4}} |\mathbf{a}^\top \mathbf{X} \mathbf{b}| \leq C_2 \sigma \sqrt{d \log(1/\delta)}\right) \geq 1 - \delta$$

for some universal constant $C_2 > 0$

Operator norm of sub-Gaussian random matrix

- **Goal:** upper bounding $\sup_{\mathbf{a}, \mathbf{b} \in \mathcal{S}^{d-1}} \mathbf{a}^\top \mathbf{X} \mathbf{b}$
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for some universal constant $C_2 > 0$

- **Step 3: approximation.** By Theorem 3.6,

$$\mathbb{P}(\|\mathbf{X}\|_2 \leq 2C_2 \sigma \sqrt{d \log(1/\delta)}) \geq 1 - \delta$$

for some universal constant $C_3 > 0$

VC dimension

- Let \mathcal{F} be a class of binary functions on the domain \mathcal{X} .
- **Shattering:** a set of points $\{x_1, \dots, x_k\} \subseteq \mathcal{X}$ is shattered by \mathcal{F} if for every possible labeling $\{0, 1\}^k$, there exists a function $f \in \mathcal{F}$ that realizes the labeling.
- The **VC dimension** of \mathcal{F} , denoted $\text{VC}(\mathcal{F})$, is the largest integer k such that there exists a set of k points in \mathcal{X} that can be *shattered* by \mathcal{F} .
- Examples:
 - When $\mathcal{X} = \mathbb{R}^2$, $\mathcal{F} =$ linear classifiers, we have $\text{vc}(\mathcal{F}) = 3$
 - In general, when $\mathcal{X} = \mathbb{R}^d$, $\mathcal{F} =$ linear classifiers, then $\text{vc}(\mathcal{F}) = d + 1$

Bounding excess risk via VC dimension

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \mathbb{1}\{f(X_i) \neq Y_i\} =: R_n(f)$$

Theorem 3.8

Suppose that \mathcal{F} is a class of Boolean function with $\text{vc}(\mathcal{F}) < \infty$. Then with probability exceeding $1 - \delta$,

$$R(\hat{f}_n) - R(f^*) \leq C \sqrt{\frac{\text{vc}(\mathcal{F}) \log(1/\delta)}{n}}$$

for some universal constant $C > 0$.

Implications:

- For $\mathcal{F} =$ linear classifiers in \mathbb{R}^d , the excess risk is $O(\sqrt{d/n})$.